

Implications of the IoT:

The CPS Framework and Key Open Questions

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 - Motivation
 - Development Process
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- Open Questions affecting Standards, Policy and Ethics

Introduction to the NIST CPS Framework

- *Cyber-physical systems*: “... smart systems that include engineered interacting networks of physical and computational components.”
 - Enable innovative applications and impact multiple economic sectors
- NIST CPS PWG: Open public forum comprising a broad range of CPS and other experts to help define and shape key characteristics of CPS
 - Gain **shared understanding** of foundational concepts and unique dimensions
 - Exchange ideas and integrate research for **CPS with new functionalities**
 - Develop a comprehensive **standards and metrics** base for CPS
- NIST CPS Framework development goals:
 - Derive **a unifying framework** that covers the range of unique dimensions
 - Populate a significant portion of the CPS Framework with detail
- CPS PWG Subgroups:
 - Reference Architecture
 - Security and Privacy
 - Use Cases
 - Data Interoperability
 - Timing

Framework for Cyber-Physical Systems

Release 1.0

May 2016

Cyber Physical Systems Public Working Group

Why Build the Framework?

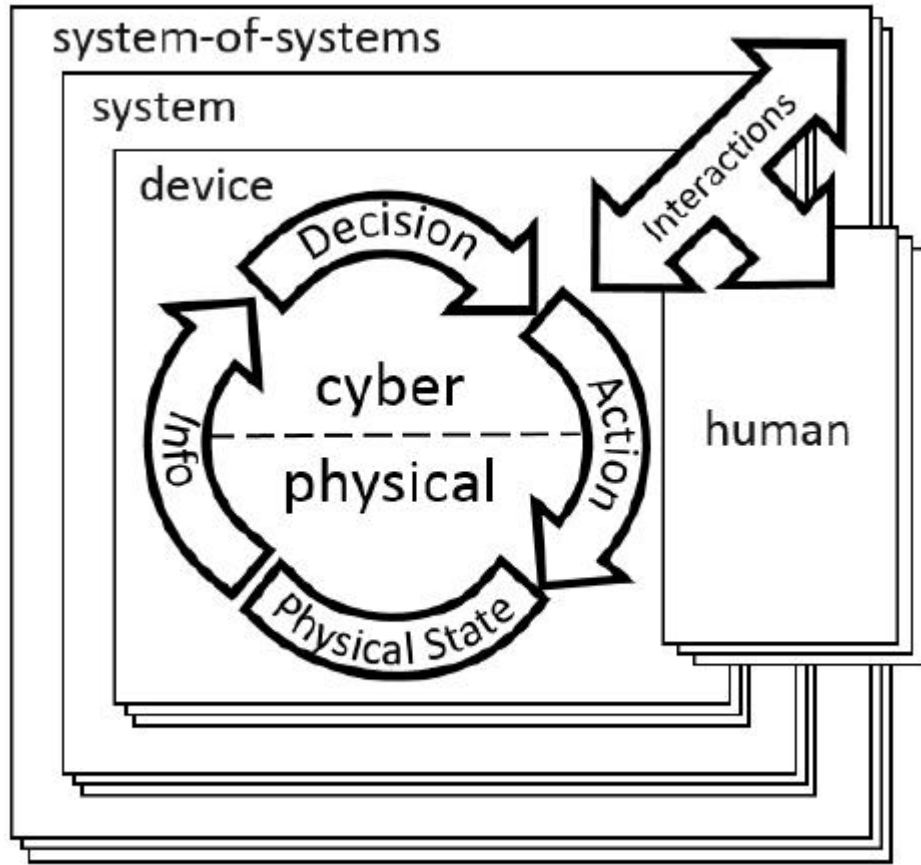
- CPS (especially the IoT) are becoming more **pervasive**
 - Trillions of devices—**growing demand** for connection and interoperability
 - High percentage with little or no **security**
- **CPS can affect the physical world**—damage, destroy, injure and kill
 - Implanted medical devices, manufacturing equipment, power generation and transmission, transportation systems, ...
- **Attacks** leveraging or targeting connected devices
 - Stuxnet, Mirai and follow-ons
 - Ransomware vs. hospitals, factories, school districts, transportation ...
- Humans must be able to **predict and control** what CPS can do
 - A true system of systems engineering problem that spans the lifecycle: conceivers, designers, developers, owners, users, customers, maintainers, ...

Quick Example: IT vs IoT/CPS Threats

	Primary Impact of Failure		Mitigation Mechanisms		
	Digital	Physical	Digital	Analog	Physical
IT System	✓		✓		
IoT/CPS	✓	✓	✓	✓	✓

*Traditional IT-based thinking is necessary but insufficient for CPS
We must think more broadly*

CPS Conceptual Model

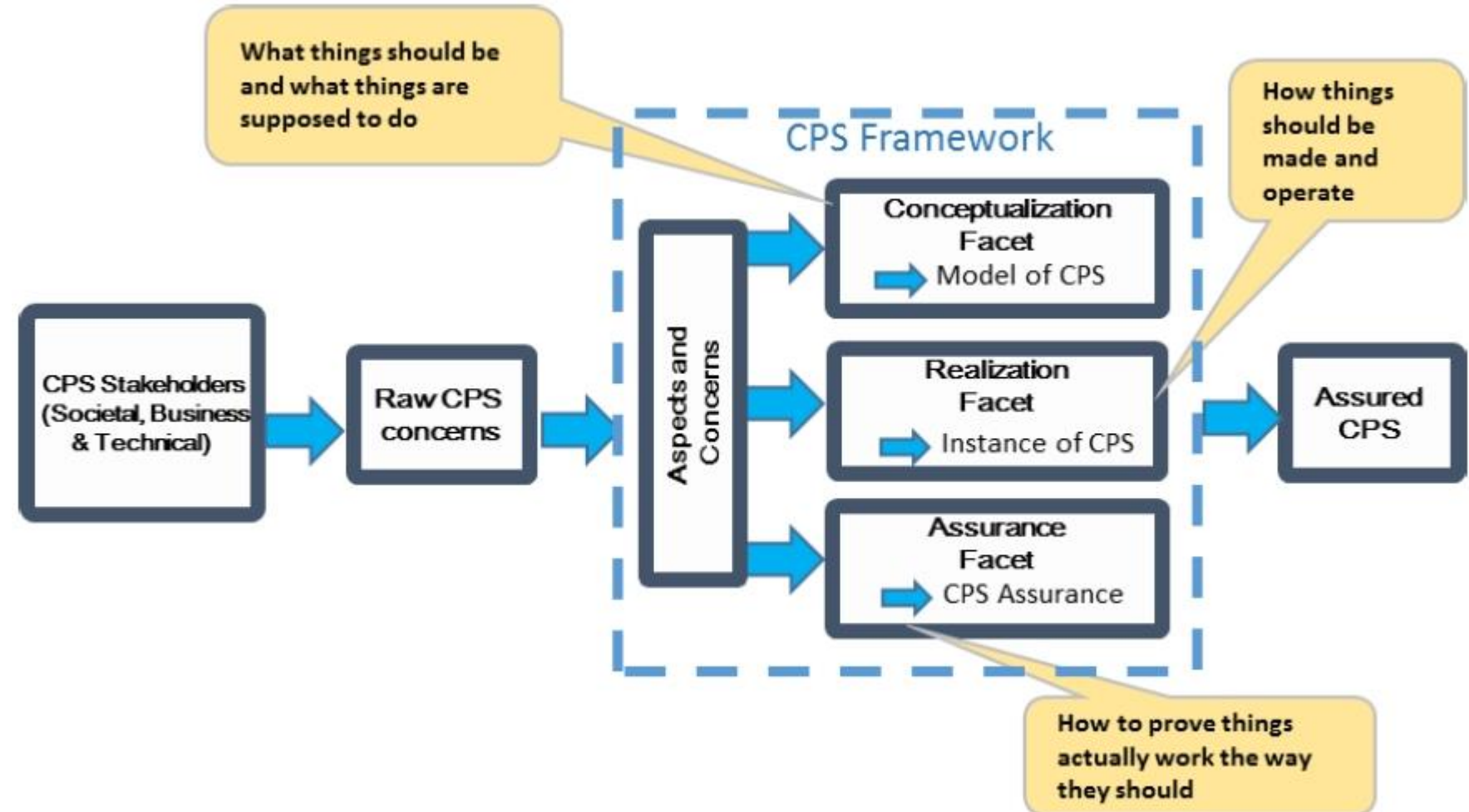


CPS:

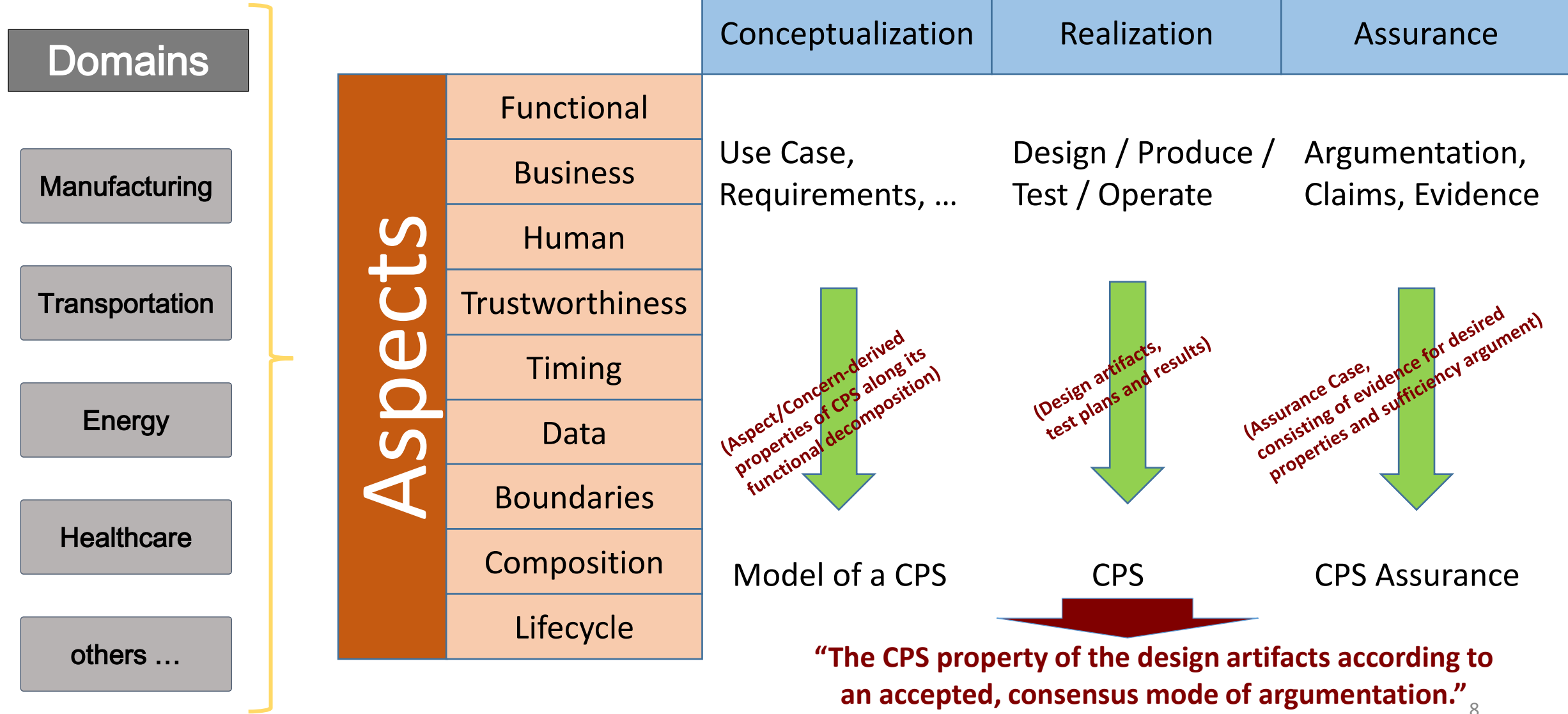
- Can **range** from simple devices to vast systems of systems
- **Interact** with other systems and humans at multiple levels: physical, logical and logical-physical
- Contain:
 - **information flows** (show state of the physical world)
 - **decision flows** (cause impacts on physical world)
- Can enable collaboration **at any scale**

CPS Framework Development Process

- Identify CPS **domains** and domain-specific **concerns**
- Identify **cross-cutting concerns**
- Analyze cross-cutting concerns to **group concerns into aspects**
- Address aspects via activities that produce artifacts in three **facets**:
 - Conceptualization
 - Realization
 - Assurance



CPS Framework Structure

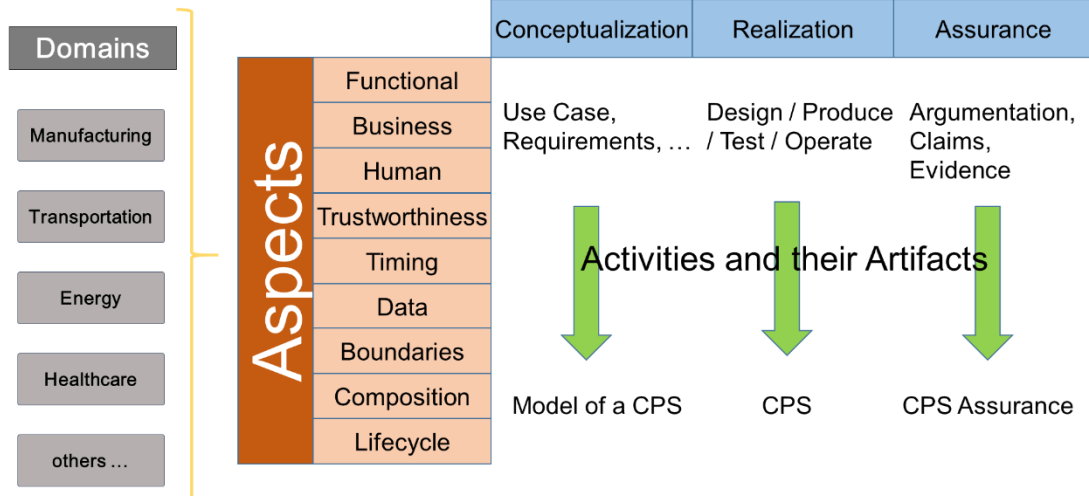


CPS Public Working Group

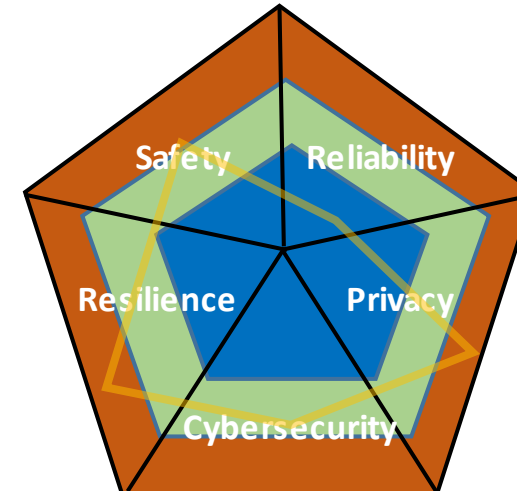
- Provides technical, concern-driven foundation for CPS/IoT: CPS Framework
- NIST leadership w/industry, academia, government
 - CPS experts in 5 working groups contributed to draft CPS Framework
 - Working Group revised draft based on public review comments
 - Version 1.0 released in May 2016
- EL, ITL, PML collaborative effort (Overall leads: Griffor, Wollman – plus Burns, Battou, Simmon, Quinn/Pillitteri, Weiss)
- Collaboration site: <https://pages.nist.gov/cpspwg/>

‘Concern-driven’: holistic, integrated approach to CPS concerns.

CPS Framework Structure



Concerns as Dimensions of CPS Measurement



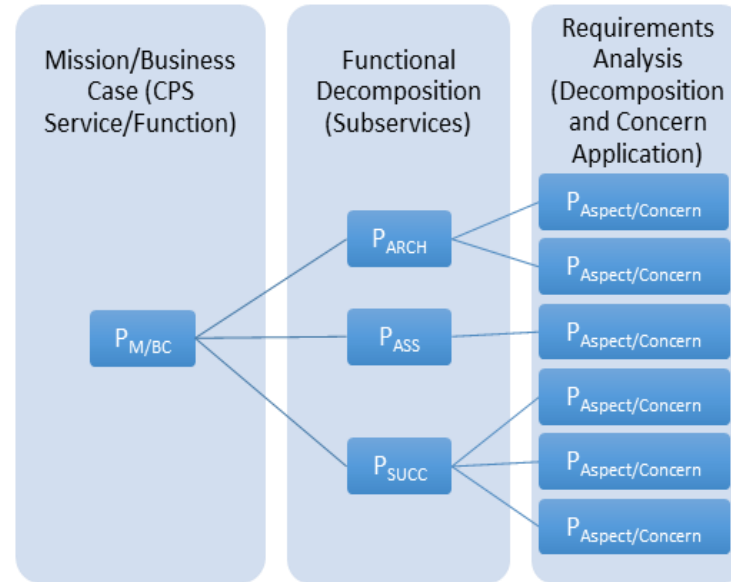
CPS Framework Mathematics

property-Tree of a CPS

Legend

$P_{M/BC}$ = Mission/Business Case
 P_{ARCH} = Integration Steps
 P_{ASS} = Assumptions
 P_{SUCC} = Success Criteria
 $P_{Aspect/Concern}$ = Aspect/Concern

- Branches capture the 'genealogy' of a property
- Branching gives assurance conditions for the branching node property
- Concerns may give rise to multiple properties in the Functional Decomposition
- 'Edges' should be read 'depends on' (L2R) or 'needed to satisfy' (R2L)



semantics of CPS Framework

$$P \in \overline{Concern}^{CPS}$$

$$\bar{P}^{CPS} = \{\text{tests } T \text{ for } P\}$$

$$Supp_M(T) = \{\text{measurement support } \mu_1, \dots, \mu_k \text{ of } T\}$$

$$\overline{Evidence}^{CPS}(P) = \sum_{T \in \bar{P}^{CPS}} \bar{T}^{CPS}$$

... defines **composition of concerns**

$$\overline{C_1 * C_2}^{CPS} = \overline{C_1}^{CPS} \cup \overline{C_2}^{CPS}$$

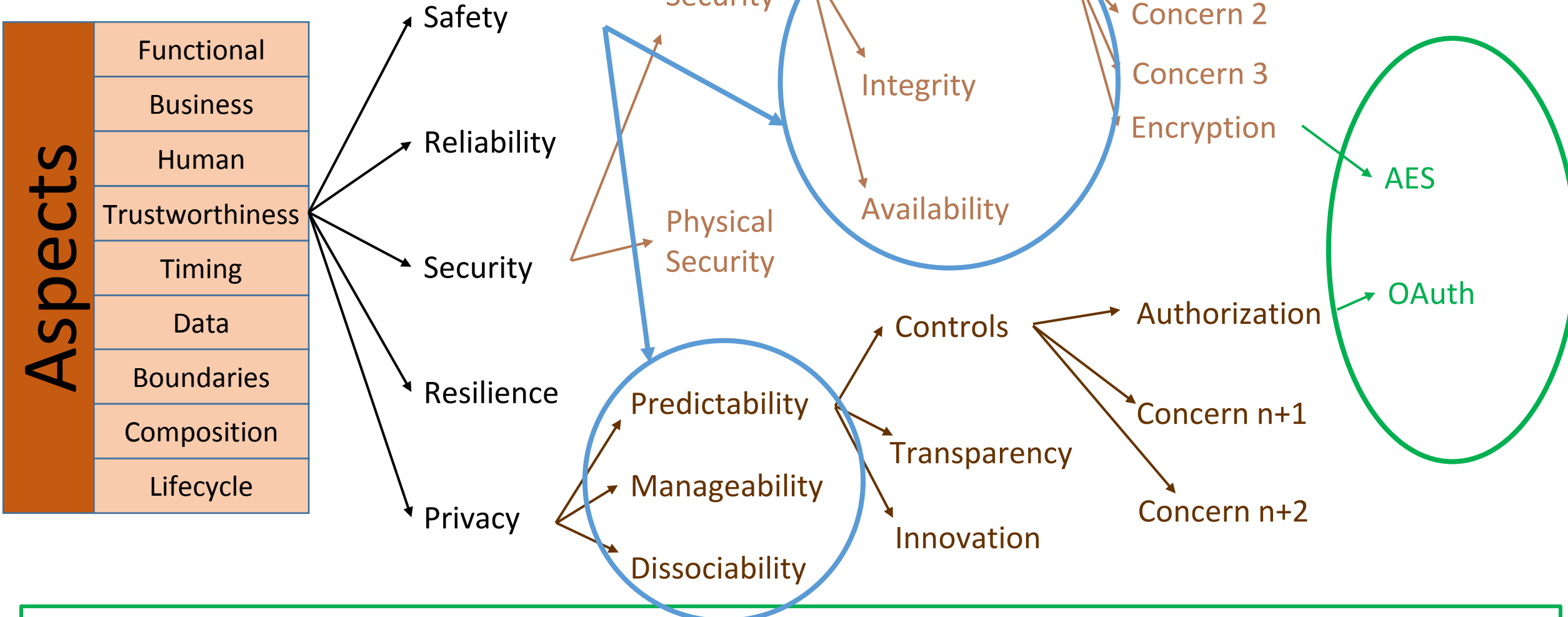
formal methods for assurance of a CPS

$\langle d, e, a \rangle \in P(CPS) \equiv_{Def}$ design element d , test evidence e are sufficient based on argument a to conclude that the CPS satisfies P

$$\overline{Assurance Case}^{CPS} = \sum_{C \in \overline{Aspect}^{CPS}} \sum_{P \in \overline{C}^{CPS}} \sum_{d \in \overline{Design}^{CPS}} \sum_{e \in \overline{Evidence(P)}^{CPS}} \overline{Argumentation}^{CPS}(P)$$

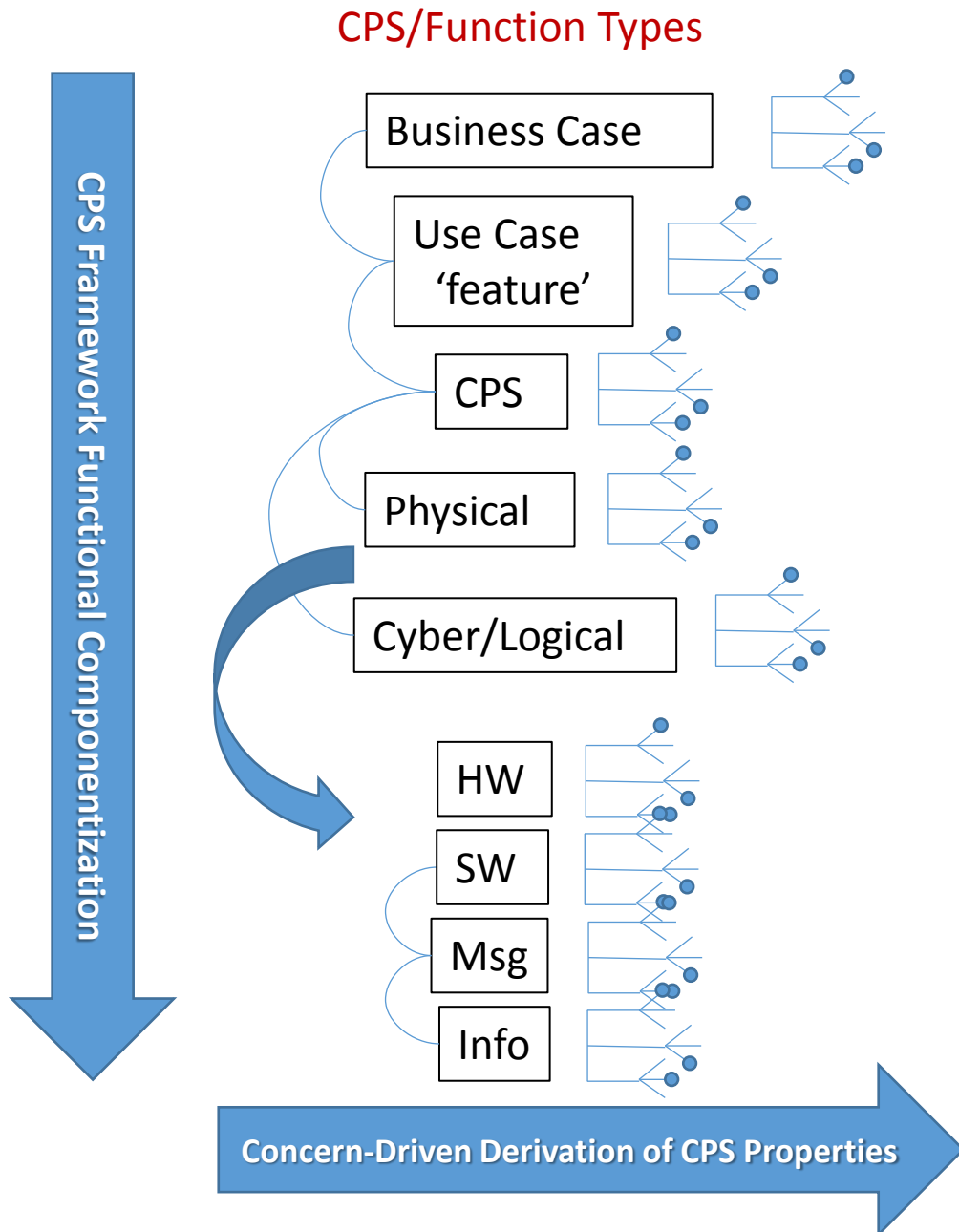
CPS Aspect/Concern/Property Tree

CPS Aspects and Concerns



A secure, privacy protected message exchange might consist of the simultaneous (set of) properties:
{Trustworthiness.Security.Cybersecurity.Confidentiality.Encryption.AES, Trustworthiness.Privacy.Predictability.Controls.Authorization.OAuth}

Decomposing a CPS in the CPS Framework



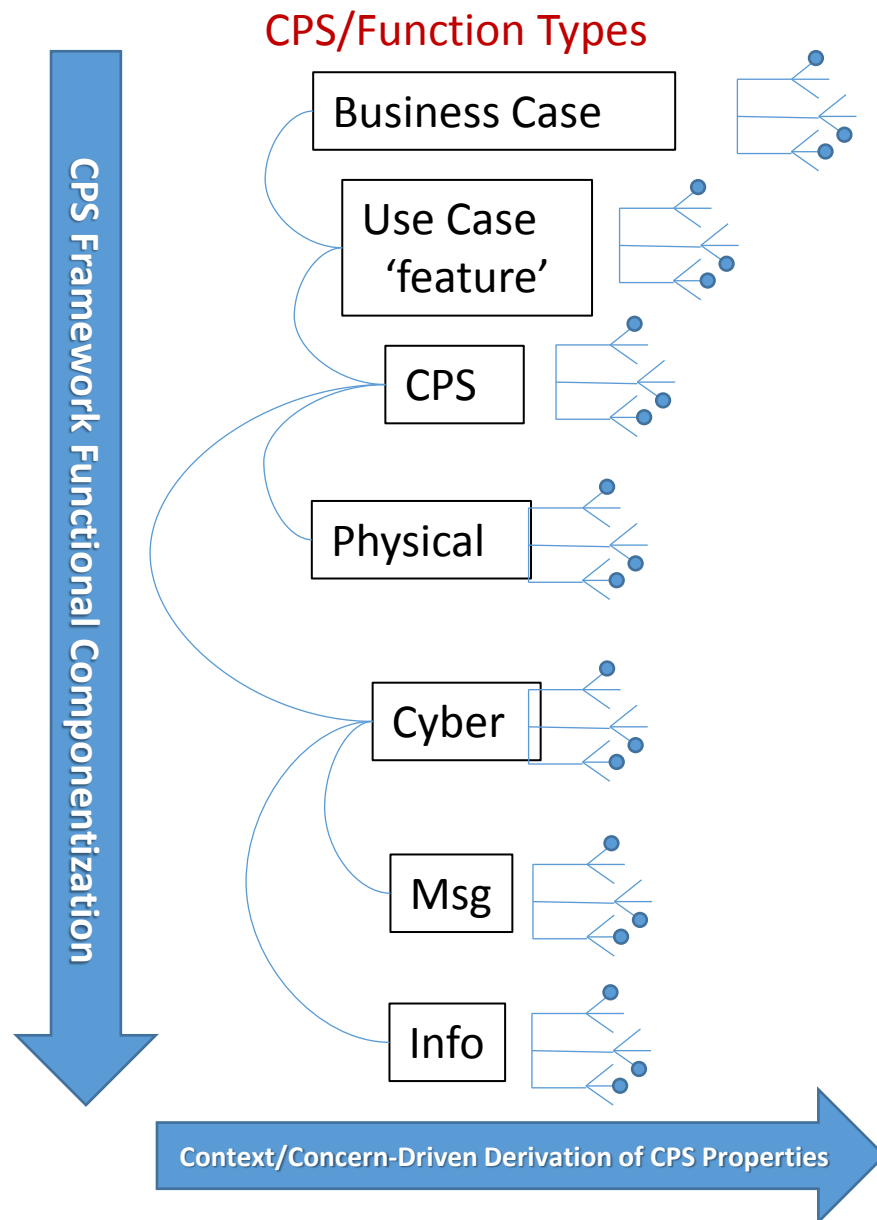
Function Types correspond to:

- input/output characteristics
- methods/tools used to develop and reason about the functions

Including:

- Business Case (content and constraints)
- Use Case (feature/function)
- CPS (cyber-physical subsystems)
- Physical functions
- Cyber/logical functions
- Allocation to SW/HW
- Message and Signal

Framework Functional Decomposition



Properties of System Functions (Automatic Emergency Braking)

AEB – vehicle provides automated collision safety function

AEB – vehicle provides/maintains safe stopping

AEB –braking function reacts as required

AEB – friction function provides appropriate friction

AEB – stopping algorithm provided safe stopping

AEB – messaging function receives distance to obstacles and speed from propulsion function

AEB – distance and speed info is understood by braking function

Functions as Sets of Properties

Hierarchy of Functions of a CPS

Properties of System Functions (AEB)

Safety – vehicle provides its function safely/without collision



Safety – vehicle provides/maintains safe stopping distance



Safety –braking function reacts as required



Safety – braking function provided appropriate friction



Safety – braking function has safe stopping algorithm



Safety – braking function receives distance to obstacles and speed from propulsion function



Safety – braking function understands distance and speed

Dependencies

Function Hierarchy

$f_{CollAvoid}$

\Downarrow

$f_{StoppingDistance}$

\Downarrow

$f_{BrakingFunction}$

\Downarrow

$f_{BrakingFriction}$

\Downarrow

$f_{SafeStopAlg}$

\Downarrow

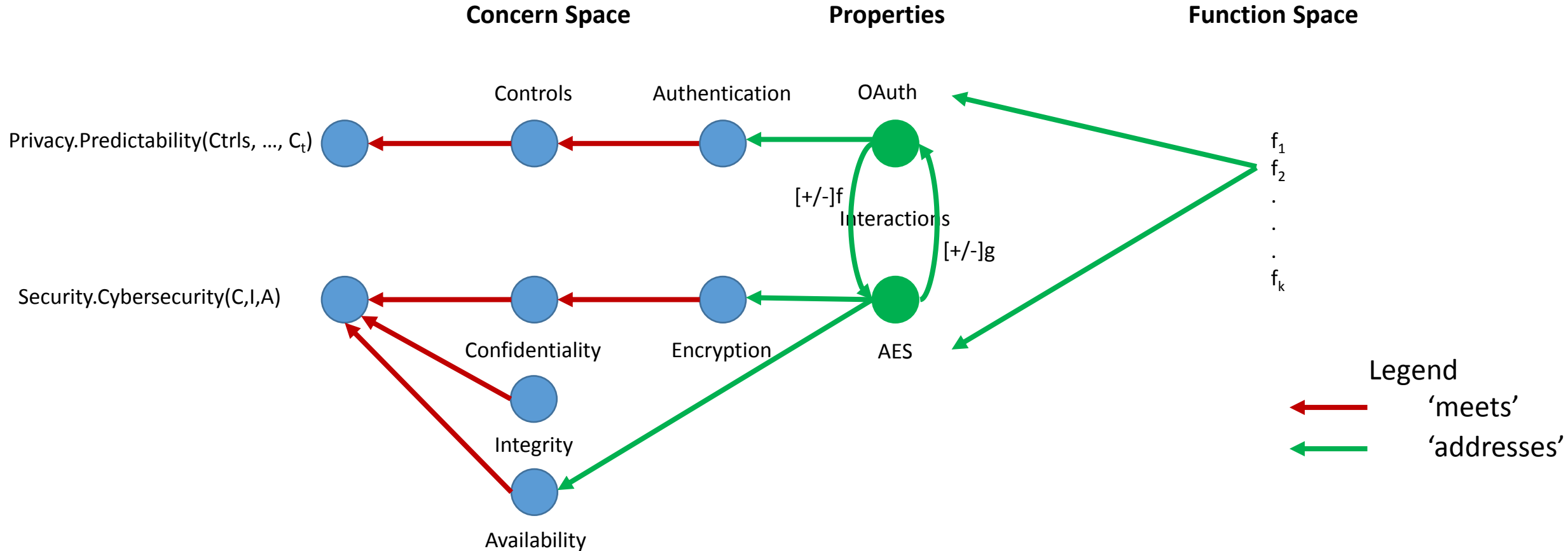
$f_{CollDistance}$ and $f_{VehicleSpeed}$

\Downarrow

$Dom(f_{BrakingFunction}) \supseteq Range(f_{CollDistance}) \cup Range(f_{VehicleSpeed})$

Function Hierarchy

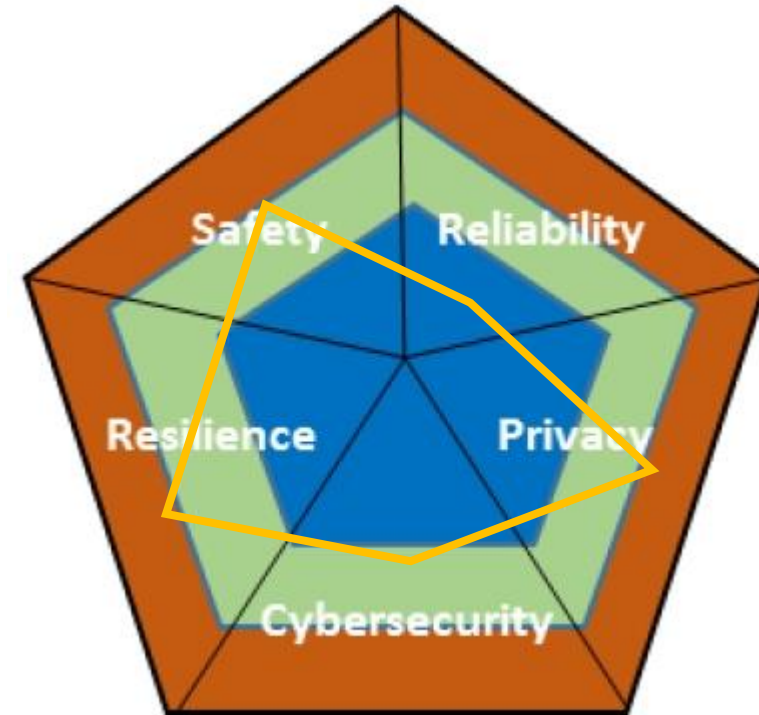
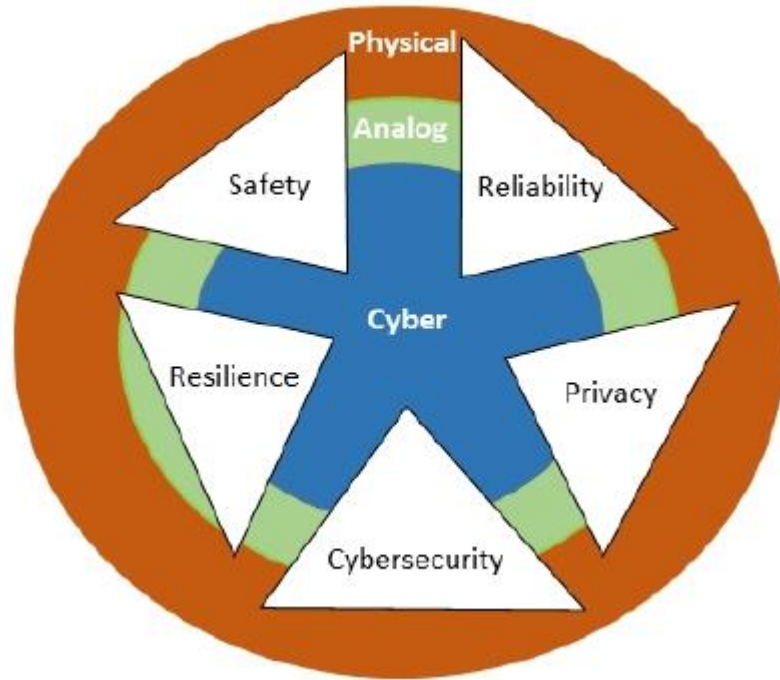
CPS Framework: The Interaction Calculus



Example Impact of one concern on another:

- Calculated using pathways through the up- or down-regulation relationships between the Properties of the CPS
- These correspond to generalized derivatives (an incremental change in one results in a negative or positive impact on the other)
- Impact is the 'generalized integral' over all pathways

Envisioning Risk in CPS--Trustworthiness



*Silo-based risk management won't work for unmanaged composition of CPS.
Integrating trustworthiness domains gives a better picture of risks and enables better mitigation*

Four (of many) Open Questions

How do we ...

- **Create useful standards** for sets of CPS that can be used to meet many different requirements serving many different needs—some of which we can't yet predict?
- Design and craft an effective **system of governance** for systems of infinitely composable CPS? What would be its scope? How would we implement it?
- Describe the **ethical responsibilities** of the people in different CPS system lifecycle roles? How do they learn about and discharge them?
- **Establish and enforce liability** for the effects of a CPS in one domain that can be connected to many other sets of CPS in other domains and nations?

Discussion

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