

# Implications of the IoT: The CPS Framework and Key Open Questions

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- Intro to the NIST CPS Framework
  - Motivation
  - Development Process
- Applying the Framework
- Open Questions affecting Standards, Policy and Ethics

# Introduction to the NIST CPS Framework

- *Cyber-physical systems*: “... smart systems that include engineered interacting networks of physical and computational components.”
  - Enable innovative applications and impact multiple economic sectors
- NIST CPS PWG: Open public forum comprising a broad range of CPS and other experts to help define and shape key characteristics of CPS
  - Gain **shared understanding** of foundational concepts and unique dimensions
  - Exchange ideas and integrate research for **CPS with new functionalities**
  - Develop a comprehensive **standards and metrics** base for CPS
- NIST CPS Framework development goals:
  - Derive a **unifying framework** that covers the range of unique dimensions
  - Populate a significant portion of the CPS Framework with detail
- **CPS PWG Subgroups:**
  - Reference Architecture
  - Security and Privacy
  - Use Cases
  - Data Interoperability
  - Timing

Framework for Cyber-Physical Systems  
Release 1.0  
May 2016

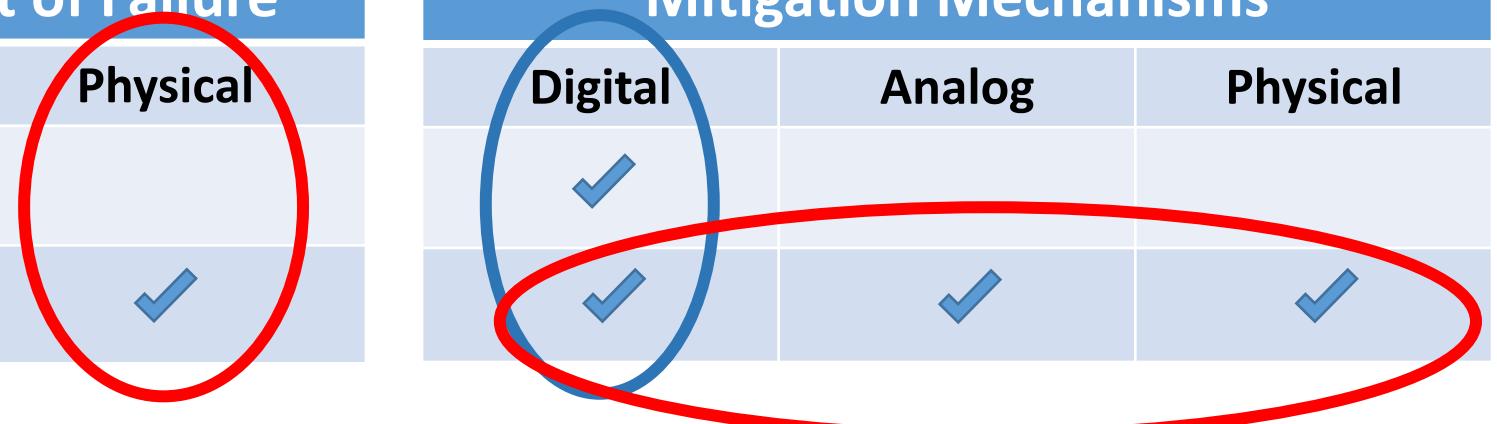
Cyber Physical Systems Public Working Group

# Why Build the Framework?

- CPS (especially the IoT) are becoming more **pervasive**
  - Trillions of devices—**growing demand** for connection and interoperability
  - High percentage with little or no **security**
- **CPS can affect the physical world**—damage, destroy, injure and kill
  - Implanted medical devices, manufacturing equipment, power generation and transmission, transportation systems, ...
- **Attacks** leveraging or targeting connected devices
  - Stuxnet, Mirai and follow-ons
  - Ransomware vs. hospitals, factories, school districts, transportation ...
- Humans must be able to **predict and control** what CPS can do
  - A true system of systems engineering problem that spans the lifecycle: conceivers, designers, developers, owners, users, customers, maintainers, ...

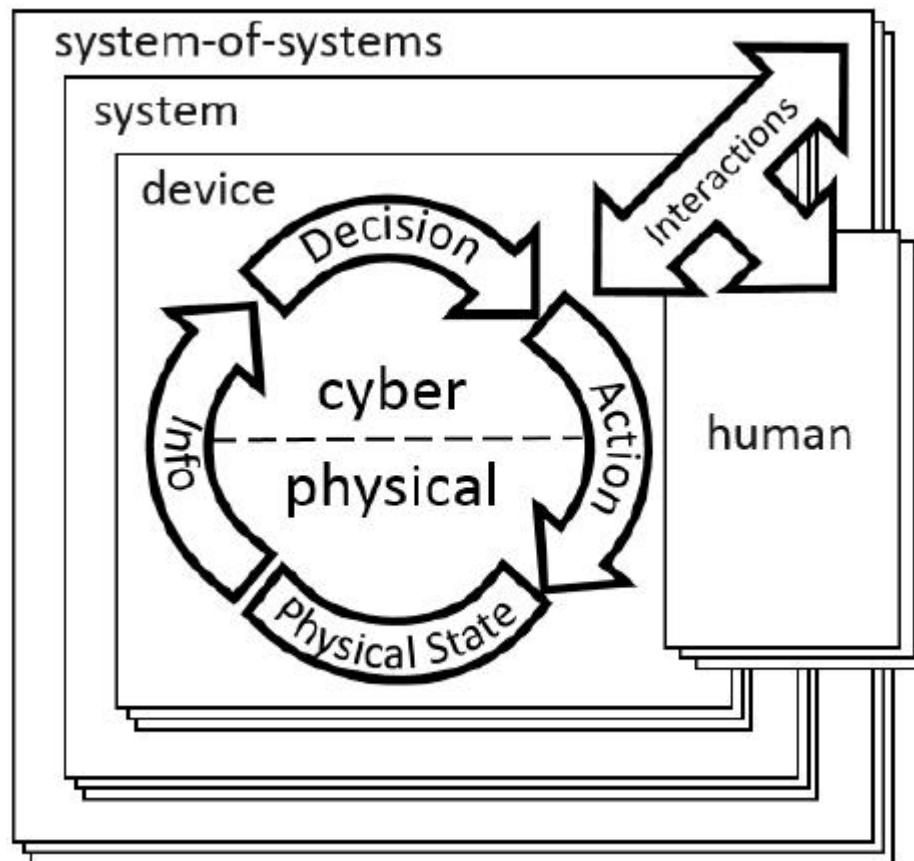
# Quick Example: IT vs IoT/CPS Threats

	Primary Impact of Failure		Mitigation Mechanisms		
	Digital	Physical	Digital	Analog	Physical
IT System	✓				
IoT/CPS	✓	✓	✓	✓	✓



*Traditional IT-based thinking is necessary but insufficient for CPS  
We must think more broadly*

# CPS Conceptual Model

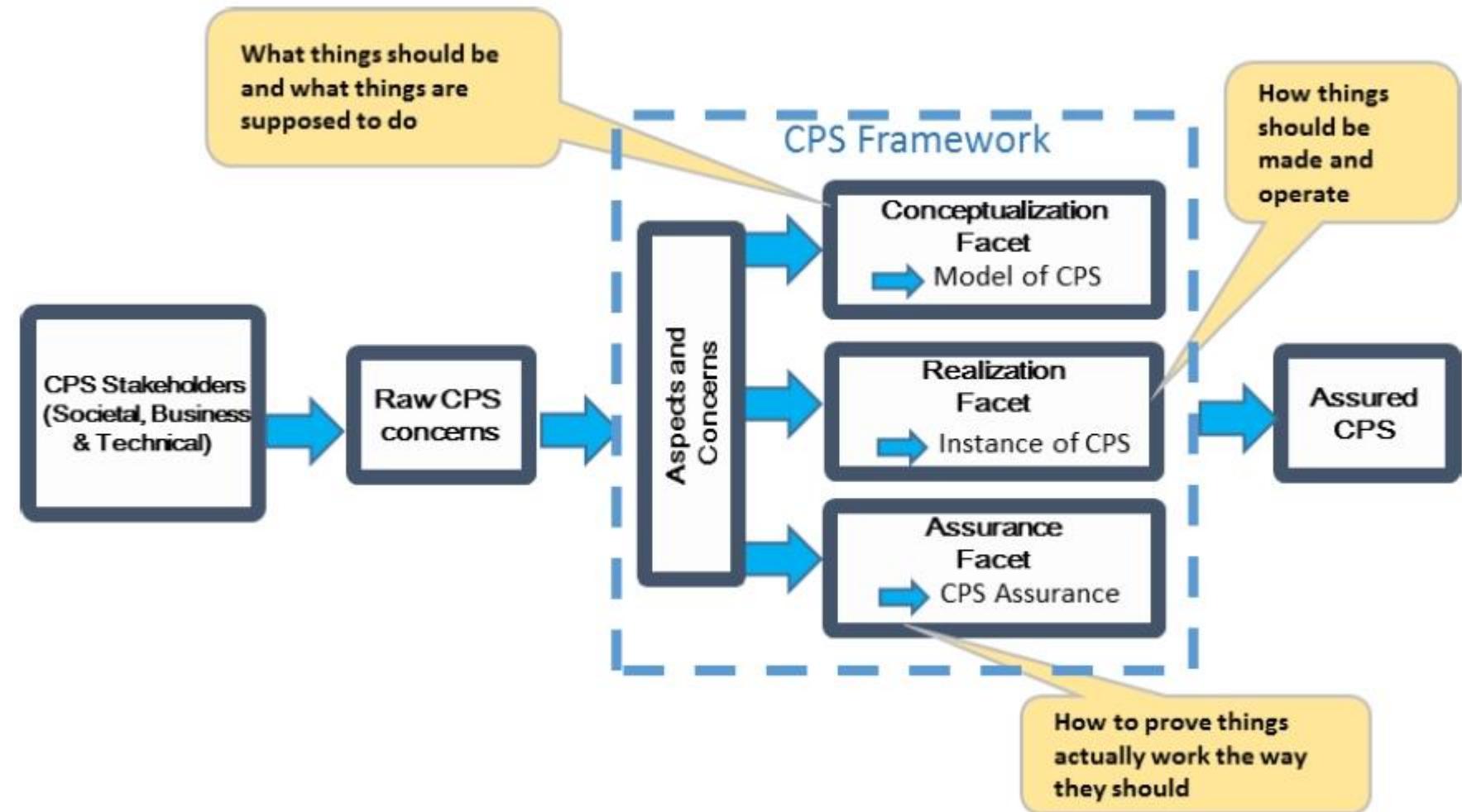


CPS:

- Can **range** from simple devices to vast systems of systems
- **Interact** with other systems and humans at multiple levels: physical, logical and logical-physical
- Contain:
  - **information flows** (show state of the physical world)
  - **decision flows** (cause impacts on physical world)
- Can enable collaboration **at any scale**

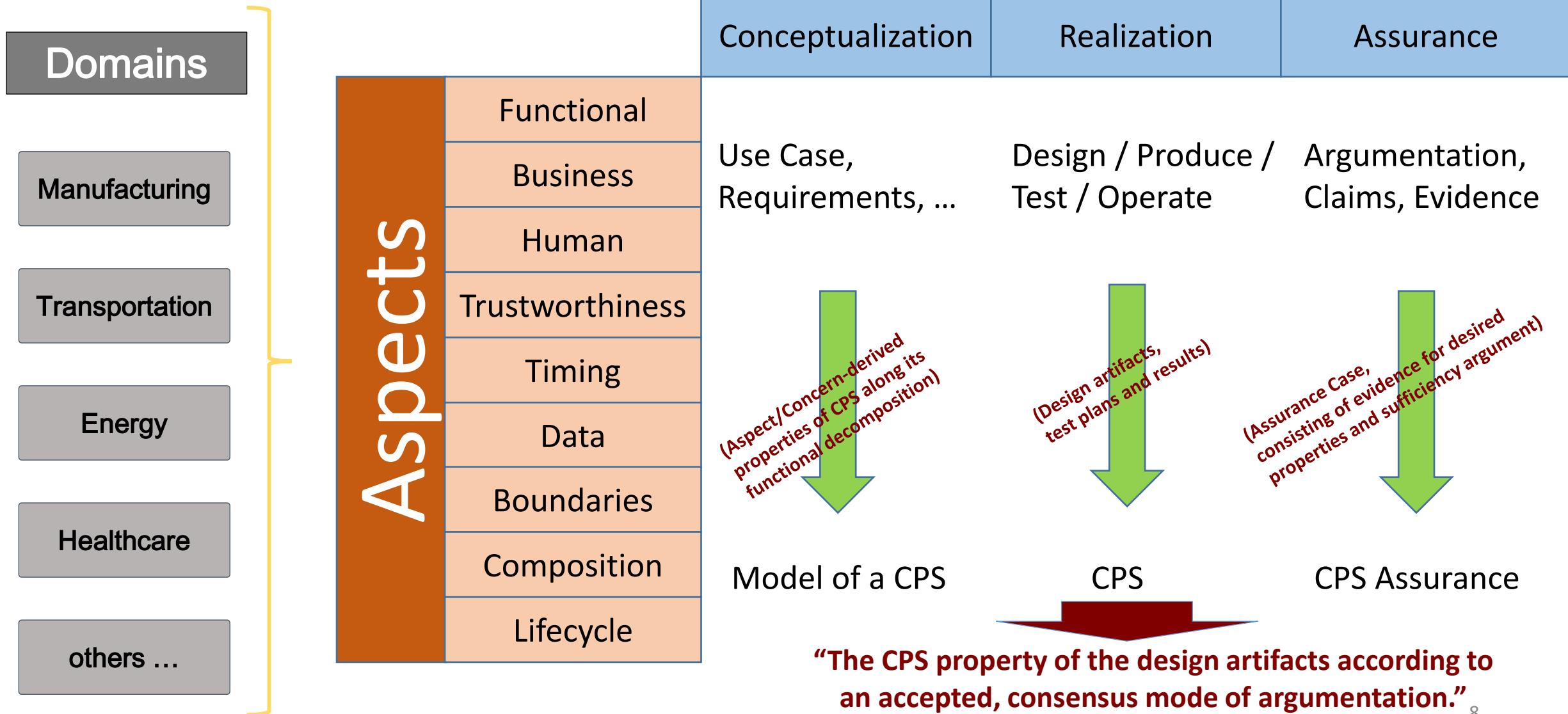
# CPS Framework Development Process

- Identify CPS **domains** and domain-specific **concerns**
- Identify **cross-cutting concerns**
- Analyze cross-cutting concerns to **group concerns into aspects**
- Address aspects via activities that produce artifacts in three **facets**:
  - Conceptualization
  - Realization
  - Assurance



# CPS Framework Structure

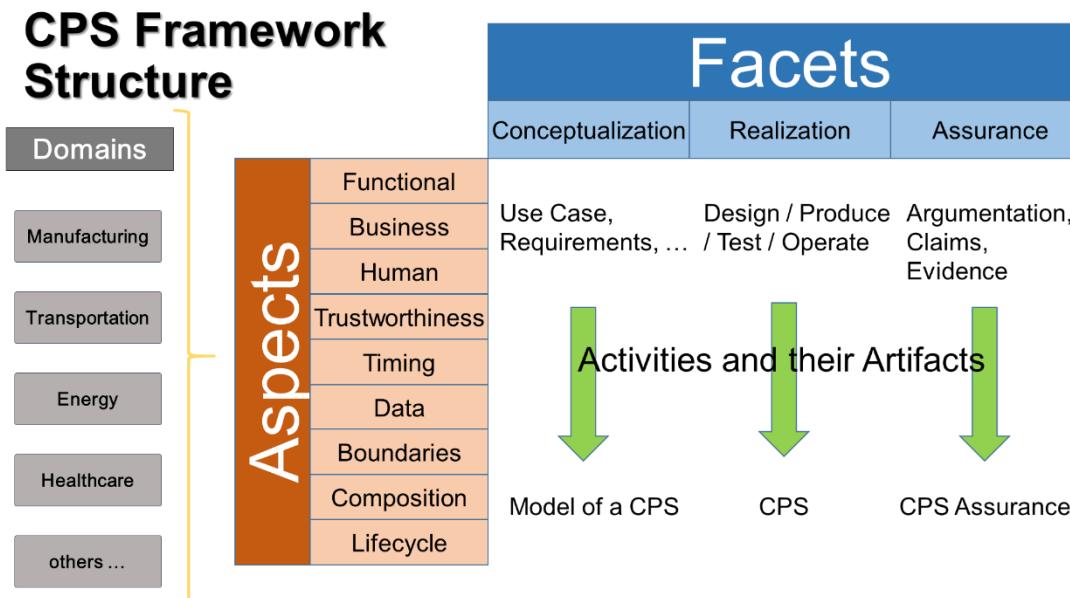
# Facets



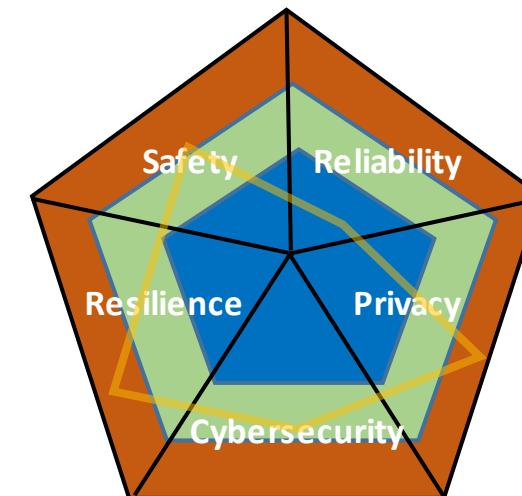
# CPS Public Working Group

- Provides technical, concern-driven foundation for CPS/IoT: CPS Framework
- NIST leadership w/industry, academia, government
  - CPS experts in 5 working groups contributed to draft CPS Framework
  - Working Group revised draft based on public review comments
  - Version 1.0 released in May 2016
- EL, ITL, PML collaborative effort (Overall leads: Griffor, Wollman – plus Burns, Battou, Simmon, Quinn/Pillitteri, Weiss)
- Collaboration site: <https://pages.nist.gov/cpspwg/>

***'Concern-driven': holistic, integrated approach to CPS concerns.***



**Concerns as Dimensions of CPS Measurement**



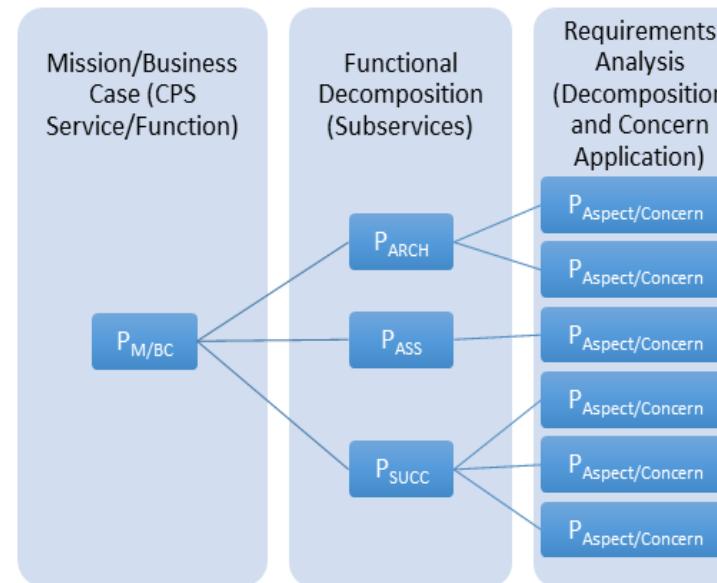
# CPS Framework Mathematics

## property-Tree of a CPS

### Legend

$P_{M/BC}$  = Mission/Business Case  
 $P_{ARCH}$  = Integration Steps  
 $P_{ASS}$  = Assumptions  
 $P_{SUCC}$  = Success Criteria  
 $P_{Aspect/Concern}$  = Aspect/Concern

- Branches capture the 'genealogy' of a property
- Branching gives assurance conditions for the branching node property
- Concerns may give rise to multiple properties in the Functional Decomposition
- 'Edges' should be read 'depends on' (L2R) or 'needed to satisfy' (R2L)



## semantics of CPS Framework

$$P \in \overline{Concern}^{CPS}$$

$$\overline{P}^{CPS} = \{tests T for P\}$$

$$Supp_M(T) = \{measurement support \mu_1, \dots, \mu_k of T\}$$

$$\overline{Evidence}^{CPS}(P) = \sum_{T \in \overline{P}^{CPS}} \overline{T}^{CPS}$$

... defines **composition of concerns**

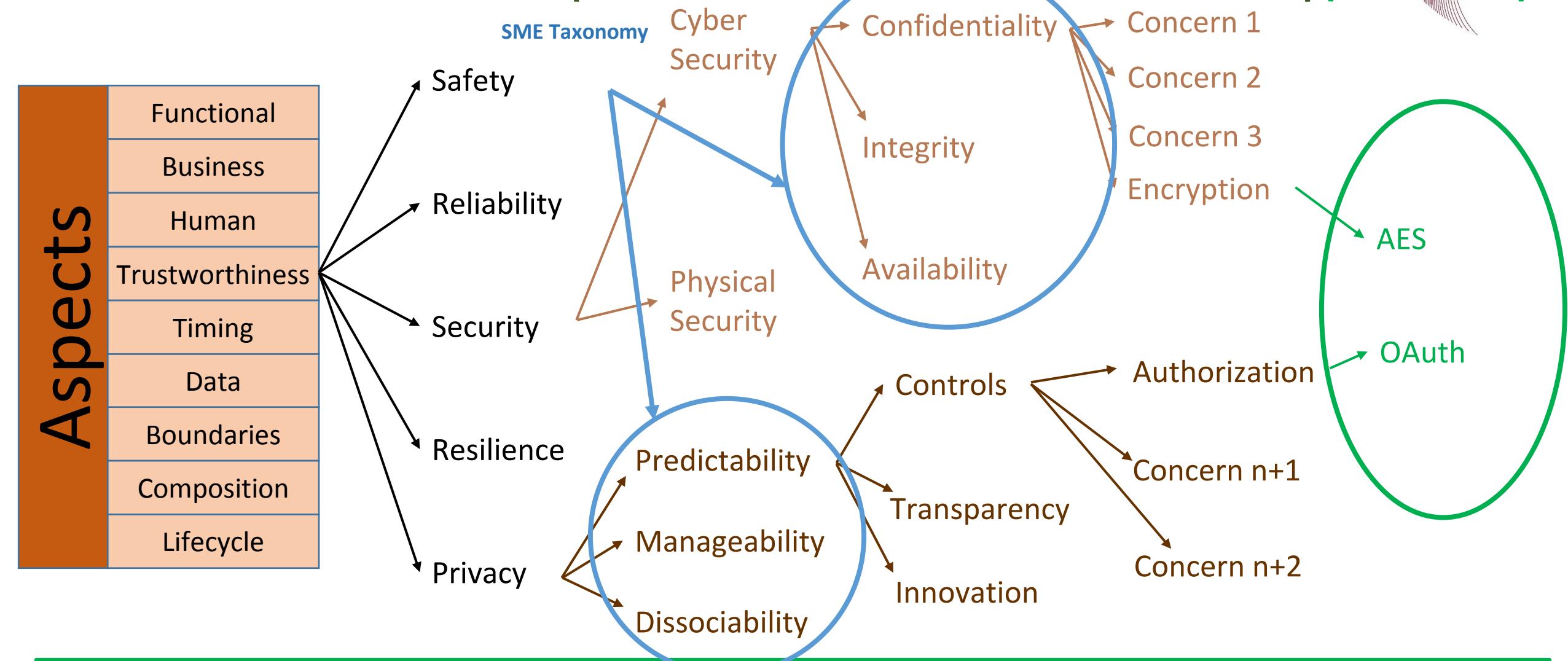
$$\overline{C_1 * C_2}^{CPS} = \overline{C_1}^{CPS} \cup \overline{C_2}^{CPS}$$

## formal methods for assurance of a CPS

$\langle d, e, a \rangle \in P(CPS) \equiv_{Def}$  design element  $d$ , test evidence  $e$  are sufficient based on argument  $a$  to conclude that the CPS satisfies  $P$

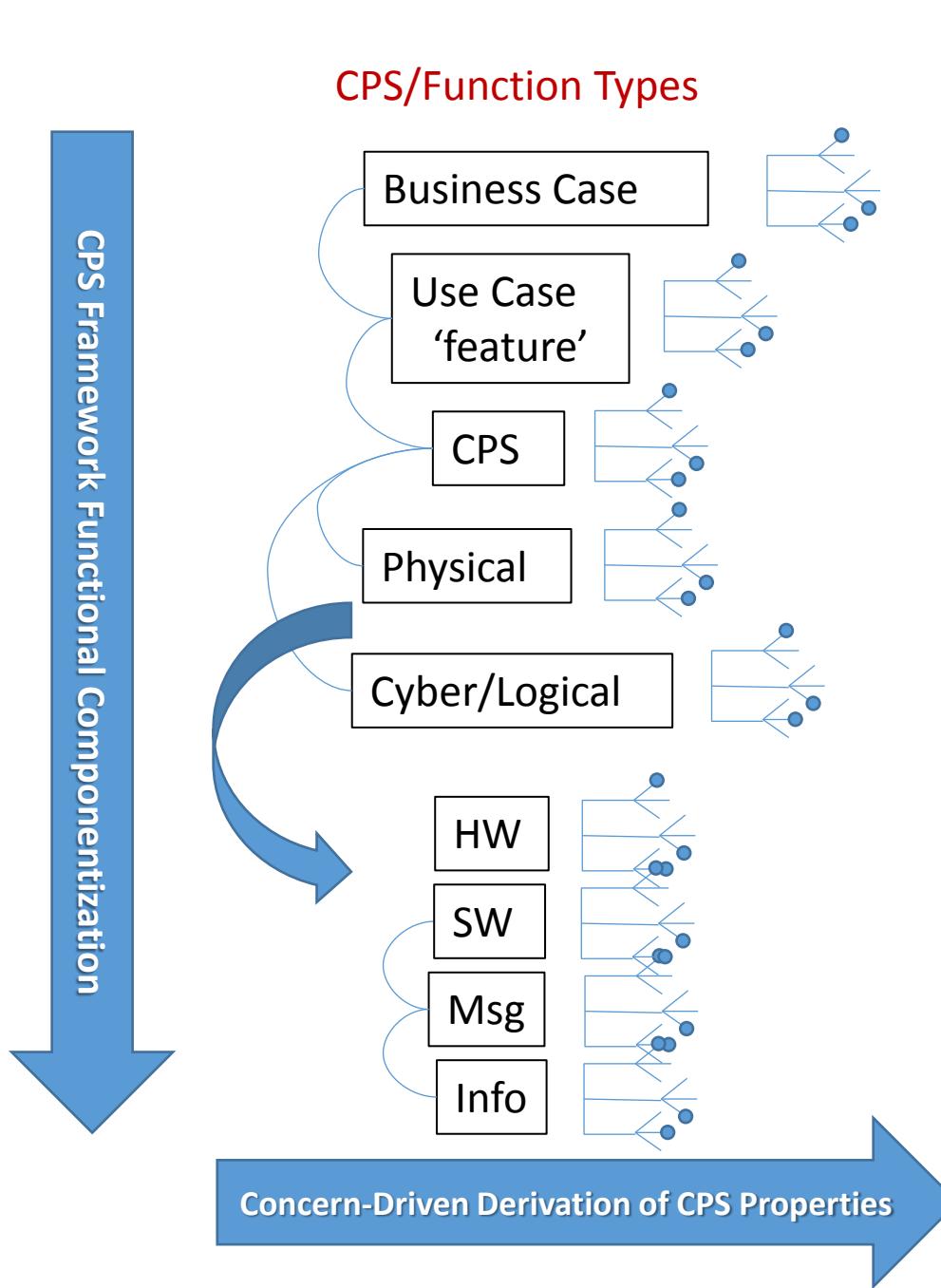
$$\overline{Assurance Case}^{CPS} = \sum_{C \in \overline{Aspect}^{CPS}} \sum_{P \in \overline{C}^{CPS}} \sum_{d \in \overline{Design}^{CPS}} \sum_{e \in \overline{Evidence(P)}^{CPS}} \overline{Argumentation}^{CPS}(P)$$

# CPS Aspect/Concern/Property Tree



A secure, privacy protected message exchange might consist of the simultaneous (set of) properties:

{Trustworthiness.Security.Cybersecurity.Confidentiality.Encryption.AES, Trustworthiness.Privacy.Predictability.Controls.Authorization.OAuth}



# Decomposing a CPS in the CPS Framework

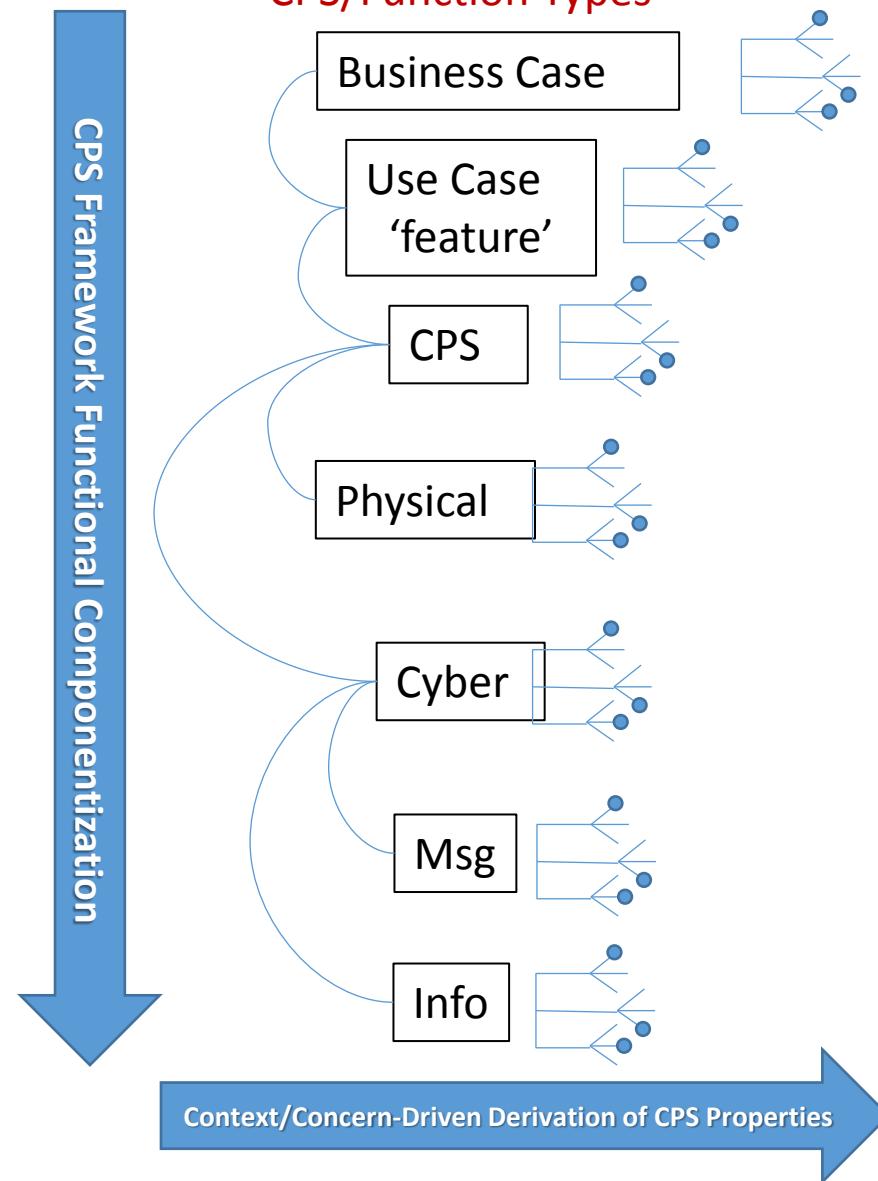
Function Types correspond to:

- input/output characteristics
- methods/tools used to develop and reason about the functions

Including:

- Business Case (content and constraints)
- Use Case (feature/function)
- CPS (cyber-physical subsystems)
- Physical functions
- Cyber/logical functions
- Allocation to SW/HW
- Message and Signal

# Framework Functional Decomposition



- Properties of System Functions (Automatic Emergency Braking)**
- AEB – vehicle provides automated collision safety function
  - AEB – vehicle provides/maintains safe stopping
  - AEB – braking function reacts as required
  - AEB – friction function provides appropriate friction
  - AEB – stopping algorithm provided safe stopping
  - AEB – messaging function receives distance to obstacles and speed from propulsion function
  - AEB – distance and speed info is understood by braking function
- Functions as Sets of Properties**

# Hierarchy of Functions of a CPS

## Properties of System Functions (AEB)

Safety – vehicle provides its function safely/without collision



Safety – vehicle provides/maintains safe stopping distance



Safety – braking function reacts as required



Safety – braking function provided appropriate friction



Safety – braking function has safe stopping algorithm



Safety – braking function receives distance to obstacles and speed from propulsion function



Safety – braking function understands distance and speed

Dependencies

## Function Hierarchy

$f_{CollAvoid}$



$f_{StoppingDistance}$



$f_{BrakingFunction}$



$f_{BrakingFriction}$



$f_{SafeStopAlg}$



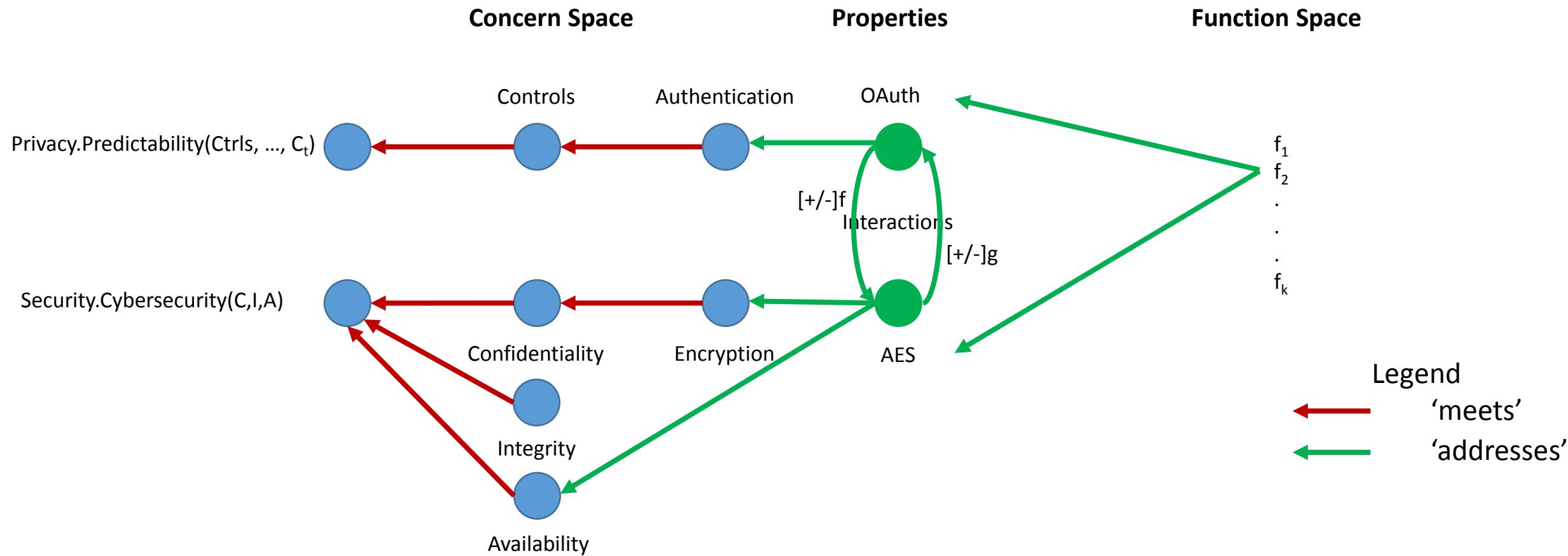
$f_{CollDistance}$  and  $f_{VehicleSpeed}$



$Dom(f_{BrakingFunction}) \supseteq Range(f_{CollDistance}) \cup Range(f_{VehicleSpeed})$

Function Hierarchy

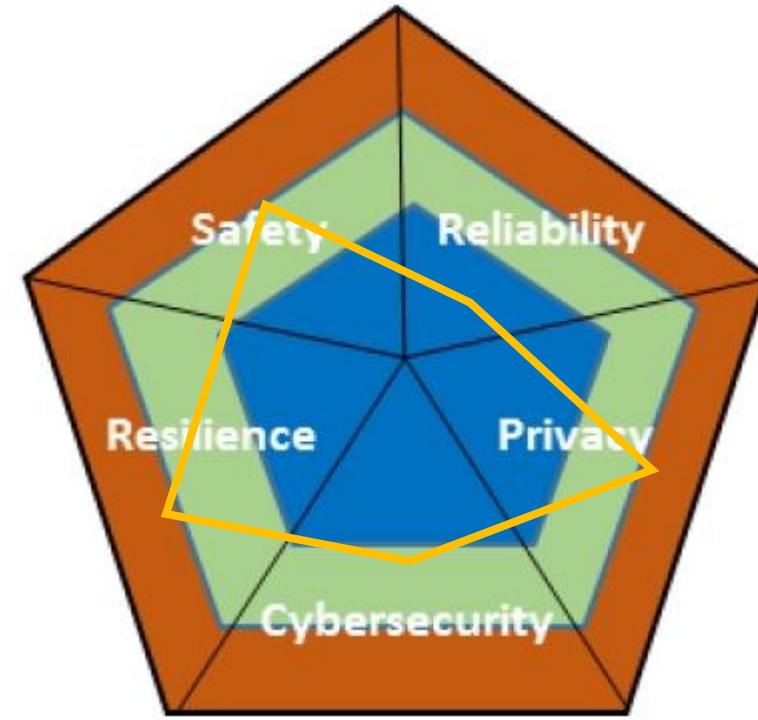
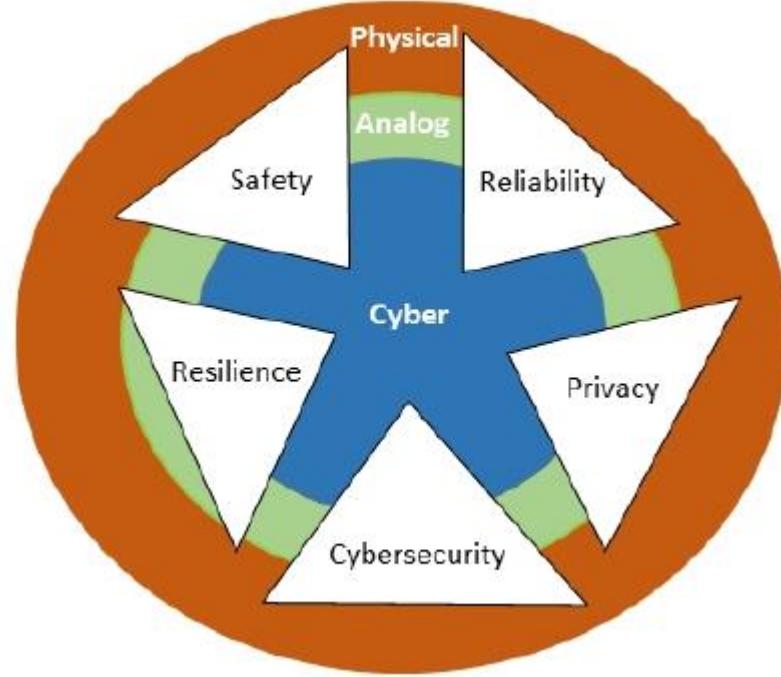
# CPS Framework: The Interaction Calculus



Example Impact of one concern on another:

- Calculated using pathways through the up- or down-regulation relationships between the Properties of the CPS
- These correspond to generalized derivatives (an incremental change in one results in a negative or positive impact on the other)
- Impact is the 'generalized integral' over all pathways

# Envisioning Risk in CPS--Trustworthiness



*Silo-based risk management won't work for unmanaged composition of CPS.*

*Integrating trustworthiness domains gives a better picture of risks and enables better mitigation*

# Four (of many) Open Questions

How do we ...

- **Create useful standards** for sets of CPS that can be used to meet many different requirements serving many different needs—some of which we can't yet predict?
- Design and craft an effective **system of governance** for systems of infinitely composable CPS? What would be its scope? How would we implement it?
- Describe the **ethical responsibilities** of the people in different CPS system lifecycle roles? How do they learn about and discharge them?
- **Establish and enforce liability** for the effects of a CPS in one domain that can be connected to many other sets of CPS in other domains and nations?



# Discussion

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